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Introduction to Linear Algebra by Hefferon

One.I.1 Solving Linear Systems, Part One

One.I.1 Solving Linear Systems, Part Two

One.I.2 Describing Solution Sets, Part One

One.I.2 Describing Solution Sets, Part Two

One.I.3 General = Particular + Homogeneous

One.II.1 Vectors in Space

One.II.2 Vector Length and Angle Measure

One.III.1 Gauss-Jordan Elimination

One.III.2 The Linear Combination Lemma

Two.I.1 Vector Spaces, Part One

Two.I.1 Vector Spaces, Part Two

Two.I.2 Subspaces, Part One

Two.I.2 Subspaces, Part Two

Two.II.1 Linear Independence, Part One

Two.II.1 Linear Independence, Part Two

Two.III.1 Basis, Part One

Two.III.1 Basis, Part Two

Two.III.2 Dimension

Two.III.3 Vector Spaces and Linear Systems

Three.I.1 Isomorphism, Part One

Three.I.1 Isomorphism, Part Two

Three.I.2 Dimension Characterizes Isomorphism

Three.II.1 Homomorphism, Part One

Three.II.1 Homomorphism, Part Two

Three.II.2 Range Space and Null Space, Part One

Three.II.2 Range Space and Null Space, Part Two.

Three.II Extra Transformations of the Plane

Three.III.1 Representing Linear Maps, Part One.

Three.III.1 Representing Linear Maps, Part Two

Three.III.2 Any Matrix Represents a Linear Map

Three.IV.1 Sums and Scalar Products of Matrices

Three.IV.2 Matrix Multiplication, Part One

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Conclusion

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Seating

Class start

Alan Edelman's speech about Gilbert Strang

Gilbert Strang's introduction

Solving linear equations

Visualization of four-dimensional space

Nonzero Solutions

Finding Solutions

**Elimination Process** 

Introduction to Equations

**Finding Solutions** 

Solution 1

Rank of the Matrix

In appreciation of Gilbert Strang

Congratulations on retirement

Personal experiences with Strang

Life lessons learned from Strang

Gil Strang's impact on math education

Gil Strang's teaching style

Gil Strang's legacy

Congratulations to Gil Strang

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Rules for Matrix Multiplication

Matrix Multiplication

How To Multiply Two Matrices

Multiplying a Matrix by a Vector

Rule for Block Multiplication

Matrix Has no Inverse

Conclusions

Compute a Inverse

Gauss Jordan

Elimination Steps

Elimination

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What Does It Mean for Two Vectors To Be Orthogonal

**Orthogonal Vectors** 

The Test for Orthogonality

What Does It Mean for Two Subspaces To Be Orthogonal

Why Is It Orthogonal to the Rows of a

Orthogonal Complements in Rn

Fundamental Theorem of Linear Algebra

Conclusion

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Two Common Span Questions

Example 1

Example 2

Solving the First Type of Span Problem

Solving the Second Type of Span Problem

General Approaches and Advice

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Introduction

Example

Solution

Questions

Relation between R and N

Creating an example

Row Reduced Form R

Full Column Rank

Is there always a solution

What is the complete solution

**Natural Symmetry** 

Elimination

Existence

Free variables

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Rectangular Matrix Example

Elimination

Rank

Solution

**Special Solutions** 

**Pivot Variables** 

Matrix R

**Pivot Columns** 

**Null Space** 

**Natural Solution** 

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