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One.I.1 Solving Linear Systems, Part One

One.I.1 Solving Linear Systems, Part Two

One.I.2 Describing Solution Sets, Part One

One.I.2 Describing Solution Sets, Part Two

One.I.3 General = Particular + Homogeneous

One.II.1 Vectors in Space

One.II.2 Vector Length and Angle Measure

One.III.1 Gauss-Jordan Elimination

One.III.2 The Linear Combination Lemma

Two.I.1 Vector Spaces, Part One

Two.I.1 Vector Spaces, Part Two

Two.I.2 Subspaces, Part One

Two.I.2 Subspaces, Part Two

Two.II.1 Linear Independence, Part One

Two.II.1 Linear Independence, Part Two

Two.III.1 Basis, Part One

Two.III.1 Basis. Part Two

Two.III.2 Dimension

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Three.I.1 Isomorphism, Part One

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Three.I.2 Dimension Characterizes Isomorphism

Three.II.1 Homomorphism, Part One

Three.II.1 Homomorphism, Part Two

Three.II.2 Range Space and Null Space, Part One

Three.II.2 Range Space and Null Space, Part Two.

Three.II Extra Transformations of the Plane

Three.III.1 Representing Linear Maps, Part One.

Three.III.1 Representing Linear Maps, Part Two

Three.III.2 Any Matrix Represents a Linear Map

Three.IV.1 Sums and Scalar Products of Matrices

Three.IV.2 Matrix Multiplication, Part One

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Q20, $(AB)^{-1} = A^{-1}B^{-1}$

Q37, A^100 invertible implies A is also invertible

Q41, Union of two subspaces is still a subspace

Q55, Z is a subspace of R

Q78, If A is invertible, then A is diagonalizable

Q84. Every matrix has a real eigenvalue

Q108, A symmetric matrix has only real eigenvalue

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Intro

Talent only takes you so far

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Youre not smart enough

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Linear Algebra - Vector Equations (1 of 2)

Linear Algebra - Vector Equations (2 of 2)

Linear Algebra - The Matrix Equation Ax = b (1 of 2)

Linear Algebra - The Matrix Equation Ax = b (2 of 2)

Linear Algebra - Solution Sets of Linear Systems

Linear Algebra - Linear Independence

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The Toolbox Method

Established What Relevant Equations

Recap

Solve for Unknown

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Question C

Matrix Multiplication

Create a Matrix

Question 5

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