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Introduction

Vibration

Nonlinear Dynamics

Summary

Natural frequencies

Experimental modal analysis

Effect of damping

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Introduction

Selecting the appropriate equations

Horizontal displacement

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Consistency Check

General Solution

Differential Equation

Initial Conditions

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Newton's Three Laws of Motion

The First Law

Inertial Frame

Second Law

The Inertial Mass

Operational Definition of Inertial Mass

Newton's Third Law

Review of Vectors

Graphical Method

Multiply a Vector by a Negative Number

Product of a Negative Number and a Vector

Subtraction of Vectors

Example 1

Unit Vector

Change of Vector Components under Rotation

Rotation about Z Axis

Vector Product

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Basic Terminology

Rectilinear Motion

Variable Acceleration Motion

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